

Distributed Artificial Reality Environment

D.A.R.E

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Outline

- What is DARE ?
- Software packages description
- Communication paradigms
- Maintaining the dynamic shared state
- Interaction methods
- Conclusions & future work

What is DARE ?

- Software framework which implements Mixed Reality (MR) and Distributed Systems (DS) paradigms to:
 - improve development time for collaborative MR applications
 - provide a testbed for research in MR and 3D displays (e.g. data distribution, registration, calibration, virtual environment parameters assessment)
- Applications built using this framework:
 - are deployed in the Artificial Reality Center (ARC)
 - span the entire Virtuality Continuum
 - are visualized using HMDs (HMPD)

Software packages description (1)

Networking package provides

- a set of classes for fast development of scalable, real-time Mixed Reality applications on a LAN
- a novel paradigm for exchanging information through software objects
- a test-bed for development of real-time synchronization algorithms
- a test-bed in support of advanced coordination schemes for real-time networked environments

3D Display package

- provides an interface for three-dimensional displays.
- was designed around, and tested with optical see-through head mounted displays
- it interacts with several well known VR programming languages like OpenGL, SGI Performer and the Virtual Environment Software Sandbox (VESS).
- extensions of the package to account for deformable 3D objects are currently under implementation.

Sensors package

- provides a test-bed for interfacing devices that are used within MR environments.
- an application can receive device data without the need of a centralized device server
- currently, the package includes classes for optical trackers
- the package will be capable of providing device information in a variety of formats for registration and calibration in MR.

Software packages description (2)

Calibration package

- provides algorithms for determining the transformations necessary to accurately display virtual objects within an application
- the algorithms include eye-point determination, camera calibration, and optical distortion calculation
- the algorithms can be adapted for use with any two-channel stereoscopic display

Registration package

- provides algorithms for placing real and virtual objects into spatial coincidence (registration)
- provides algorithms for assessing the quality of registration

Assessment package

- includes visual perception tests aimed at assessing virtual environment system parameters
- currently includes a modified Landolt C Visual Acuity tests as well as a perceived contrast test
- will include tests which allow mapping of the contrast sensitivity function for the HMPD display across all spatial frequency channels of the retina.

Software packages description (3)

- The Base package
 - contains algebraic operation for matrices, vectors and quaternions

DARE Base Package

```

dareMatrix
-mData : dareVector
-mRows : int
-mColumns : int
+=( )
+[]()
+Identity()
+Invert()
+Transpose()
+Scale()
+Scale()
+Print()
+Print()
+setRow()
+setColumns()
+Determinant()
+getRows()
+getColumns()
+getRow()
+getColumn()
+SubMatrix()
+MatrixToQuat()
+Multiply()
+Multiply()
+Add()
+Subtract()
    
```

```

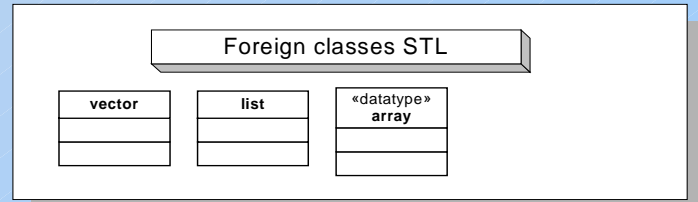
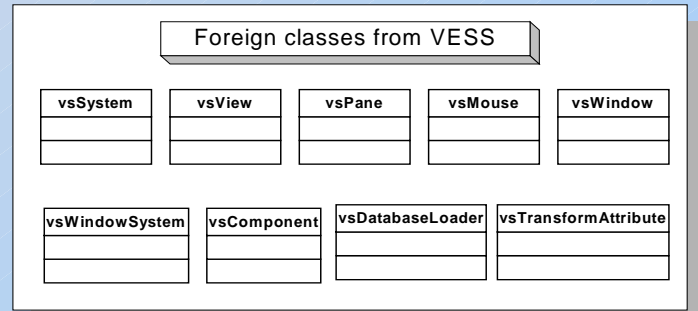
dareVector
-mHomogeneous : dareBool
-mVector : vector
+=( )
+[]()
+setHomogeneous()
+isHomogeneous()
+getNorm()
+getSize()
+Normalize()
+Invert()
+Scale()
+Print()
+Print()
+Dot()
+getAngle()
+Add()
+Subtract()
+Cross()
    
```

```

dareQuaternion
-mScalar : float
-mVector : dareVector
+=( )
+[]()
+setScalar()
+setVector()
+setQuaternion()
+setVector()
+Invert()
+Print()
+Print()
+getScalar()
+getVector()
+RotatePoint()
+QuaternionToMatrix()
+CombineQuaternions()
    
```

```

«enumeration»
dareBool
-DARE_TRUE = 1
-DARE_FALSE = 0
    
```

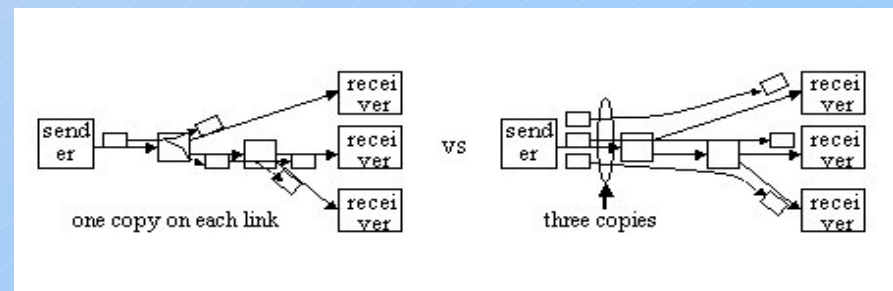
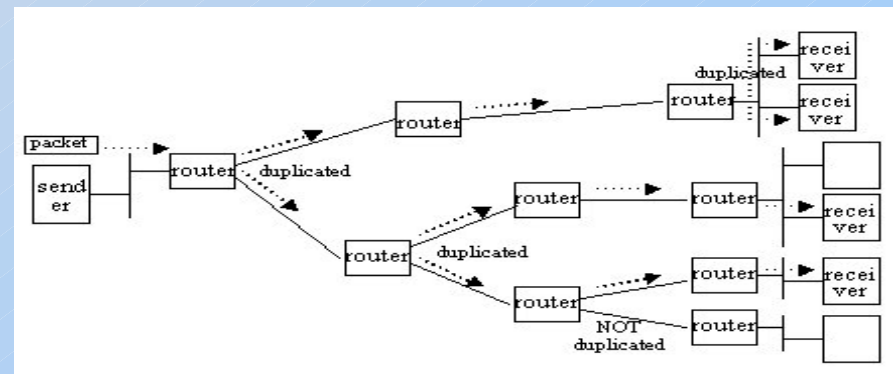
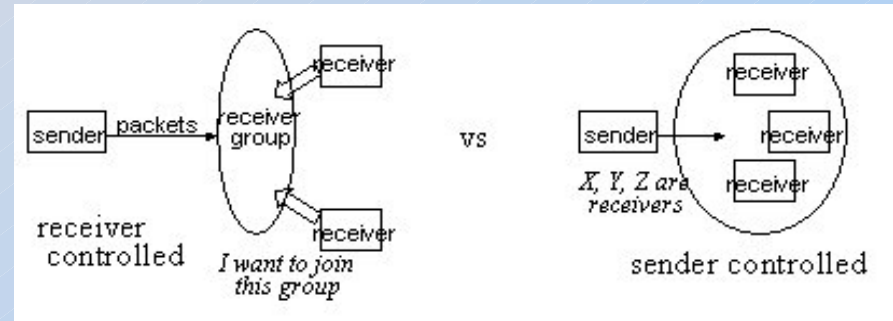


Communication (1)

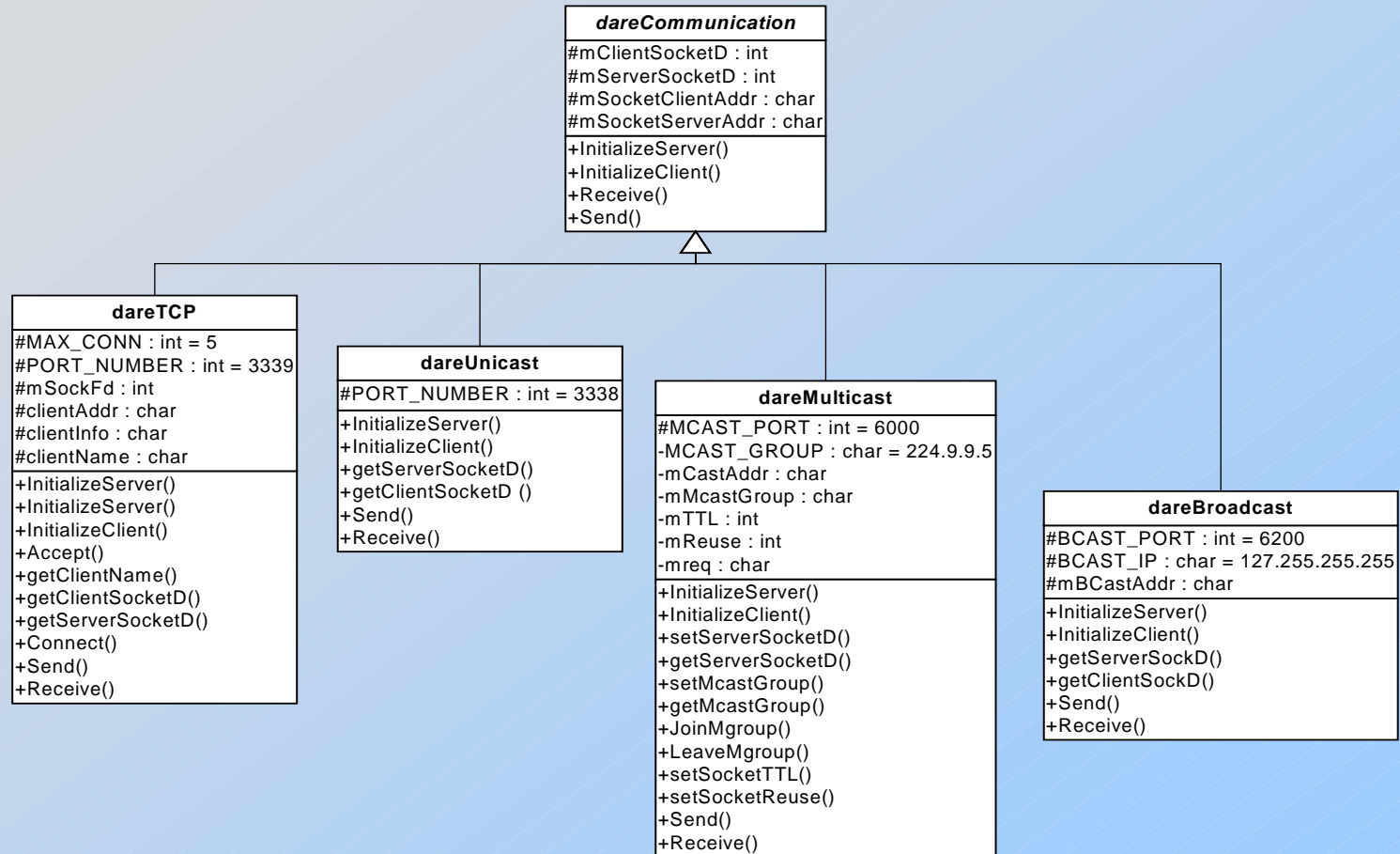
- The protocols used for network communication are:
 - TCP/IP
 - UDP/IP
- Communication paradigms:
 - Connectionless (one-to-one) - unreliable/low delay
 - Connection oriented (one-to-one) - reliable/higher delay
 - Mass distribution (one-to-many):
 - broadcast/low delay/bandwidth intensive
 - multicast/low delay/bandwidth conservation

Communication (2) – IP Multicast

- Each Receiver joins a group (instead of Sender control)
- Anybody can join any group
 - TV-like ctrl~ tune on any TV station
- IP Multicast
 - Implements mcast in IP layer
 - Packets are duplicated ONLY when necessary.
 - Addressing ~ Group Address
 - Receivers to join a group, IGMP
 - Mcast routing protocols for inter-router control
 - Slow deployment, MBONE



Network package classes (1)



Network package classes (2)

dareControlPackage
-mOX : int
-mOY : int
-mOZ : int
-modelPosition : dareVector
-modelOrientation : dareQuaternion
+setModelPosition()
+setModelPosition()
+setModelOrientation()
+setModelOrientation()
+setFileName()
+setRGBFileName()
+setMouse()
+setMouse()
+setRotTime()
+setTransTime()
+setRotSpeed()
+setRotQuat()
+getModelPosition()
+getModelOrientation()
+getFileName()
+getRGBFileName()
+getRotTime()
+getTransTime()
+getTransSpeed()
+getRotSpeed()
+getColor()
+isZoom()
+isExit()
+isReset()

dareRTT
-MAXPACKET : unsigned int = 4096
-MAXHOSTNAMELEN : unsigned int = 64
-MAXWAIT : unsigned int = 10
-rtt : double
-s : int
-packet : unsigned char
-ntransmitted : int
-tz :
-ident : int
-datalen : int
+getRtt()
+TvSub()
-pinger()
-pr_pack()
-in_cksum()

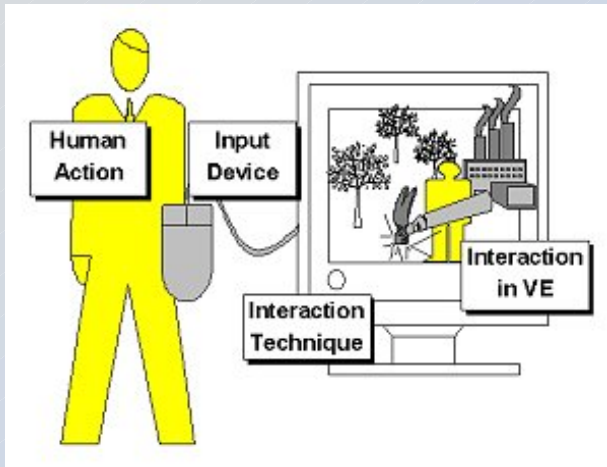
Maintaining the shared state

- The *ControlPackage* class allows instantiation of *ControlPackage* software objects
- The software objects contain information about the shared scene:
 - 3D objects position
 - 3D objects orientation
 - actions type (rotation/translation) applied on the objects
 - actions velocity
 - etc (open for sub-classing and aggregation)
- Objects can be transmitted through LAN using:
 - multicasting, broadcasting employing the client-server paradigm
 - tcp, Unicast(udp) employing peer-to-peer paradigm

Interaction methods (1)

- The definition of interaction differs according to research domain
- Human triggered interaction through a device (sensor) e.g.
 - mouse and a graphical user interface
 - position tracking sensor
 - speech recognition sensor, etc.
- Machine triggered interaction (programmed)
 - simulation loop
 - predetermined avatar behavior

Interaction methods (2) – *human triggered*



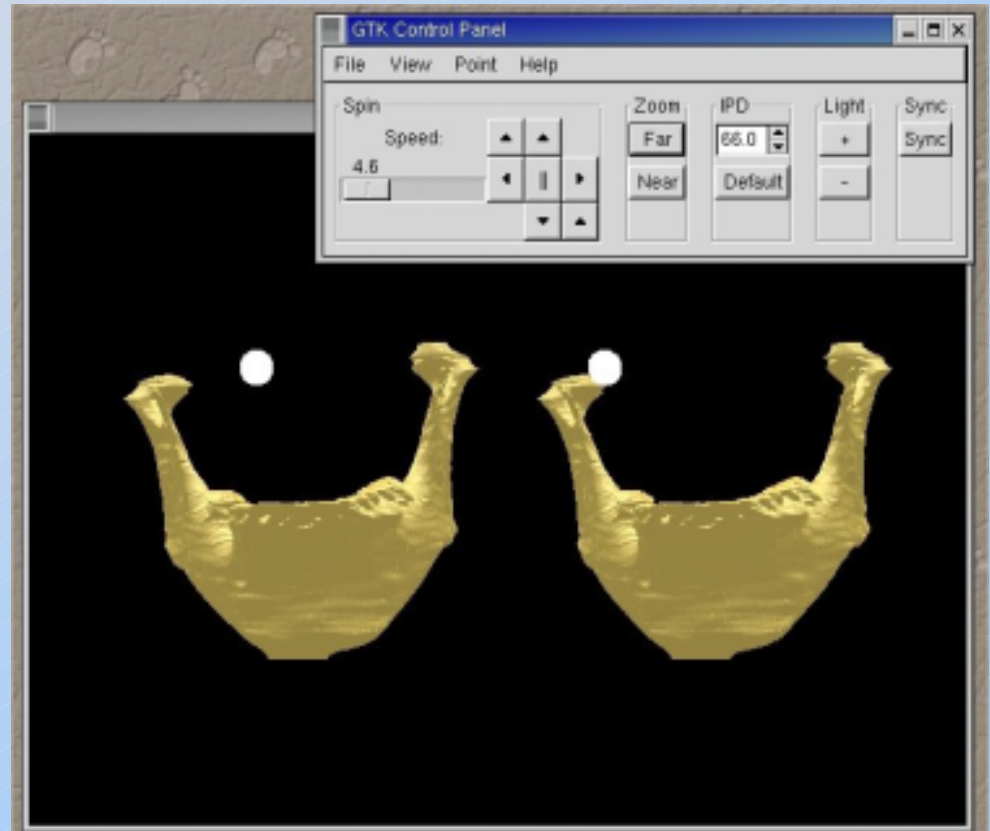
- Interaction sequence starts from human action
- Interaction is taken by means of an input device
- Executed interaction = the interaction that occurs within the virtual environment

Interaction methods (3) - *actions*

- High frequency vs. Low frequency actions
 - depends of the input device
(action freq. triggered from a mouse: www.cs.ucf.edu/~fhamza/html/MouseClicking.html)
 - Predictable vs. unpredictable actions
 - depends on the environment (static vs. dynamic)
 - direct manipulation [*Shneiderman, 82*] interfaces
 - Continuous representation of the object of interest
 - Physical actions instead of complex syntax
 - Impact on the object of interest is immediately visible
- (!) Direct manipulation interfaces are easy to use, moreover, it also reduces the cognitive load.

Interaction methods - *DARE 3D pointer*

- Small spherical pointer
- Connected to mouse device
- Left/right OZ axis
- Stereoscopic appearance



Conclusions

- DARE is an open framework, freely distributed for research in MR environments and for promoting applications for 3D displays.
- Hopefully DARE will unite the development efforts of the ODALab team members.
- DARE project will be used as reference to pursue research initiatives and to obtain financing for the research initiatives.
- DARE_V1.0_alpha released to ODALab members mid June,03.
- DARE_V1.0_beta released to ODALab members mid July,03.

Future

- DARE_V1.0 will be released soon (we all hope) and can be publicly advertised.
- More applications will start using the framework classes.

Web Page

<http://odalab.creol.ucf.edu/dare>

suggestions and comments are welcomed